# **CPU Scheduling**

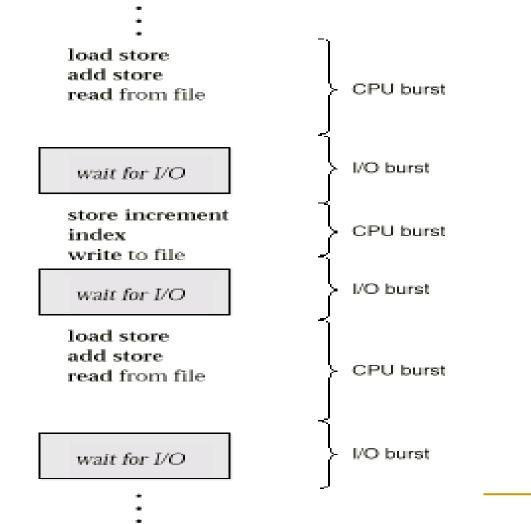
#### Introduction

- Basic Concepts
- Scheduling Criteria
- Scheduling Algorithms
- Multiple-Processor Scheduling
- Real-Time Scheduling
- Algorithm Evaluation

### **Basic Concepts**

- Maximum CPU utilization obtained with multiprogramming
- CPU–I/O Burst Cycle Process execution consists of a cycle of CPU execution and I/O wait.
- CPU burst distribution

#### Alternating Sequence of CPU And I/O Bursts



#### **CPU Scheduler**

- Selects from among the processes in memory that are ready to execute, and allocates the CPU to one of them.
- CPU scheduling decisions may take place when a process:
  - 1. Switches from running to waiting state.
  - 2. Switches from running to ready state.
  - 3. Switches from waiting to ready.
  - 4. Terminates.
- Scheduling under 1 and 4 is nonpreemptive.
- All other scheduling is *preemptive*.

#### Dispatcher

- Dispatcher module gives control of the CPU to the process selected by the short-term scheduler; this involves:
  - switching context
  - switching to user mode
  - jumping to the proper location in the user program to restart that program
- Dispatch latency time it takes for the dispatcher to stop one process and start another running.

# Scheduling Criteria

- CPU utilization keep the CPU as busy as possible
- Throughput # of processes that complete their execution per time unit
- Turnaround time amount of time to execute a particular process
- Waiting time amount of time a process has been waiting in the ready queue
- Response time amount of time it takes from when a request was submitted until the first response is produced, not output (for time-sharing environment)

### **Optimization Criteria**

- Max CPU utilization
- Max throughput
- Min turnaround time
- Min waiting time
- Min response time

#### First-Come, First-Served (FCFS). Scheduling

- Example: Process Burst Time  $P_1$ 24  $P_2$ 3  $P_3$ 3
- Suppose that the processes arrive in the order:  $P_1$ ,  $P_2$ ,  $P_3$ The Gantt Chart for the schedule is:

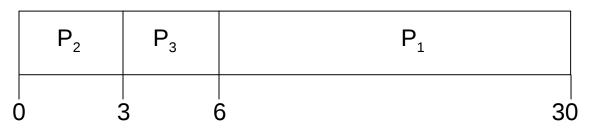
P <sub>1</sub>	P <sub>2</sub>	P <sub>3</sub>	
0 24	4 2	7 30	

- Waiting time for  $P_1 = 0$ ;  $P_2 = 24$ ;  $P_3 = 27$
- Average waiting time: (0 + 24 + 27)/3 = 17

# FCFS Scheduling (Cont.)

Suppose that the processes arrive in the order

- $P_2$ ,  $P_3$ ,  $P_1$ .
- The Gantt chart for the schedule is:



- Waiting time for  $P_1 = 6$ ;  $P_2 = 0$ ;  $P_3 = 3$
- Average waiting time: (6 + 0 + 3)/3 = 3
- Much better than previous case.
- Convoy effect short process behind long process

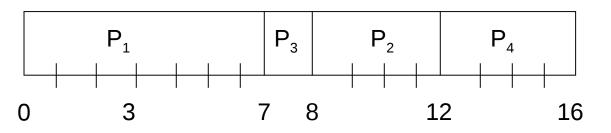
# Shortest-Job-First (SJF) Scheduling

- Associate with each process the length of its next CPU burst. Use these lengths to schedule the process with the shortest time.
- Two schemes:
  - nonpreemptive once CPU given to the process it cannot be preempted until completes its CPU burst.
  - Preemptive if a new process arrives with CPU burst length less than remaining time of current executing process, preempt. This scheme is know as the Shortest-Remaining-Time-First (SRTF).
- SJF is optimal gives minimum average waiting time for a given set of processes.

# Example of Non-Preemptive SJF

ProcessArrival Time Burst Time $P_1$ 0 $P_2$ 2 $P_2$ 2 $P_3$ 4 $P_4$ 5

#### SJF (non-preemptive)

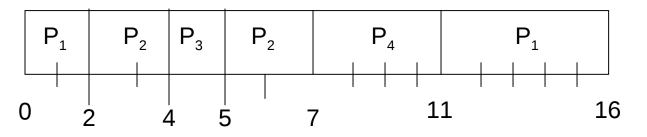


• Average waiting time = (0 + 6 + 3 + 7)/4 = 4

#### Example of Preemptive SJF(SRTF)

ProcessArrival Time Burst Time $P_1$ 0 $P_2$ 2 $P_2$ 2 $P_3$ 4 $P_4$ 5

#### SJF (preemptive)



• Average waiting time = (9 + 1 + 0 + 2)/4 = 3

# **Priority Scheduling**

- A priority number (integer) is associated with each process
- The CPU is allocated to the process with the highest priority (smallest integer  $\equiv$  highest priority).
  - Preemptive
  - nonpreemptive
- SJF is a priority scheduling where priority is the predicted next CPU burst time.
- Problem  $\equiv$  Starvation low priority processes may never execute.
- Solution  $\equiv$  Aging as time progresses increase the priority of the process.

# Round Robin (RR)

- Each process gets a small unit of CPU time (time quantum), usually 10-100 milliseconds. After this time has elapsed, the process is preempted and added to the end of the ready queue.
- If there are n processes in the ready queue and the time quantum is q, then each process gets 1/n of the CPU time in chunks of at most q time units at once. No process waits more than (n-1)q time units.
- Performance
  - □ q large  $\Rightarrow$  FIFO
  - □  $q \text{ small} \Rightarrow q \text{ must be large with respect to context switch, otherwise overhead is too high.}$

# Example: RR with Time Quantum = 20 Process Burst Time

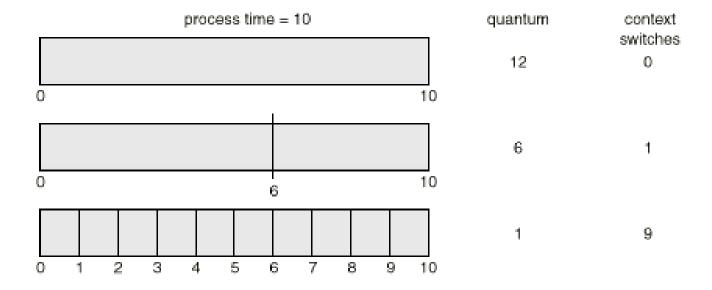
Process	<u>Burst I im</u>
$P_1$	53
$P_2$	17
$P_3$	68
$P_4$	24

The Gantt chart is:

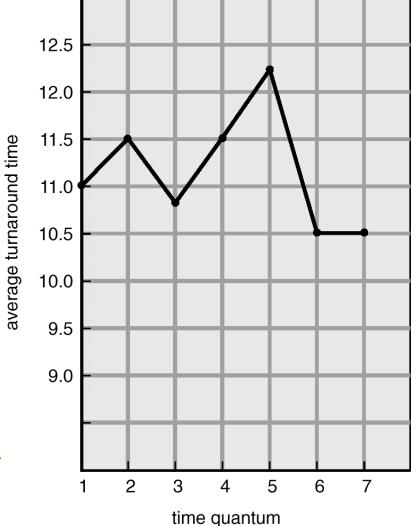
0	20	37	57	77	97	117	121	134	154	162
P <sub>1</sub>	P <sub>2</sub>	P <sub>3</sub>	P <sub>4</sub>	$P_1$	P <sub>3</sub>	P <sub>4</sub>	P <sub>1</sub>	P <sub>3</sub>	P <sub>3</sub>	

Typically, higher average turnaround than SJF, but better *response*.

#### How a Smaller Time Quantum Increases Context Switches



#### Turnaround Time Varies With The Time Quantum



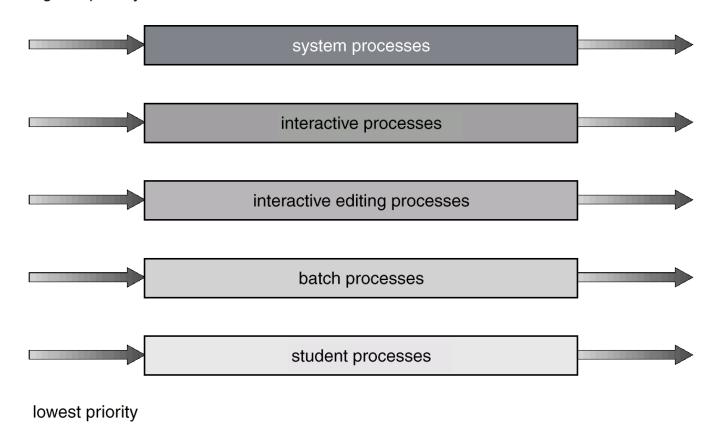
process	time
P <sub>1</sub> P <sub>2</sub> P <sub>3</sub> P <sub>4</sub>	6 3 1 7

### Multilevel Queue

- Ready queue is partitioned into separate queues: foreground (interactive) background (batch)
- Each queue has its own scheduling algorithm, foreground – RR background – FCFS
- Scheduling must be done between the queues.
  - Fixed priority scheduling; i.e., serve all from foreground then from background. Possibility of starvation.
  - Time slice each queue gets a certain amount of CPU time which it can schedule amongst its processes; i.e., 80% to foreground in RR
  - 20% to background in FCFS

# Multilevel Queue Scheduling

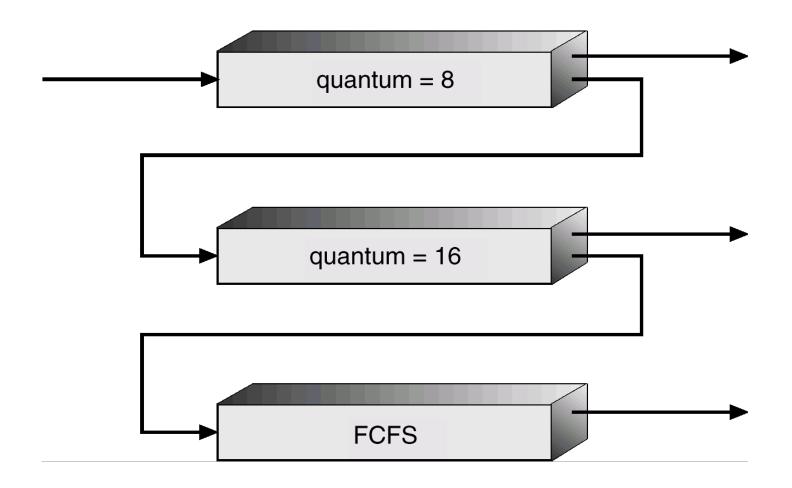
highest priority



#### Multilevel Feedback Queue

- A process can move between the various queues; aging can be implemented this way.
- Multilevel-feedback-queue scheduler defined by the following parameters:
  - number of queues
  - scheduling algorithms for each queue
  - method used to determine when to upgrade a process
  - method used to determine when to demote a process
  - method used to determine which queue a process will enter when that process needs service

#### Multilevel Feedback Queues



#### Example of Multilevel Feedback Queue

- Three queues:
  - $\Box$   $Q_0$  time quantum 8 milliseconds
  - $\Box$   $Q_1$  time quantum 16 milliseconds
  - $\Box Q_2 FCFS$
- Scheduling
  - A new job enters queue Q<sub>0</sub> which is served FCFS.
     When it gains CPU, job receives 8 milliseconds. If it does not finish in 8 milliseconds, job is moved to queue Q<sub>1</sub>.
  - At Q<sub>1</sub> job is again served FCFS and receives 16 additional milliseconds. If it still does not complete, it is preempted and moved to queue Q<sub>2</sub>.

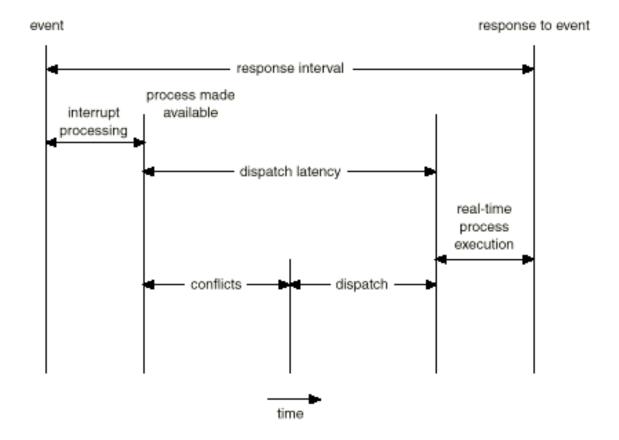
# Multiple-Processor Scheduling

- CPU scheduling more complex when multiple CPUs are available.
- Homogeneous processors within a multiprocessor.
- Load sharing
- Asymmetric multiprocessing only one processor accesses the system data structures, alleviating the need for data sharing.

### **Real-Time Scheduling**

- Hard real-time systems required to complete a critical task within a guaranteed amount of time.
- Soft real-time computing requires that critical processes receive priority over less fortunate ones.

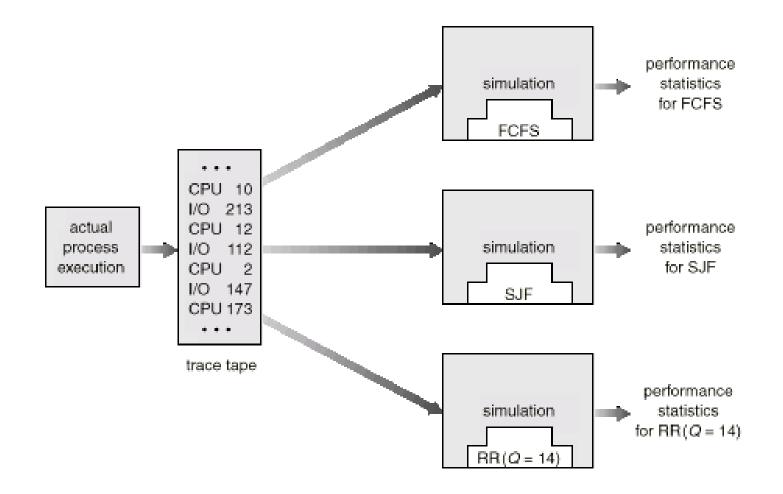
#### **Dispatch Latency**



### Algorithm Evaluation

- Deterministic modeling takes a particular predetermined workload and defines the performance of each algorithm for that workload.
- Queuing models
- Implementation

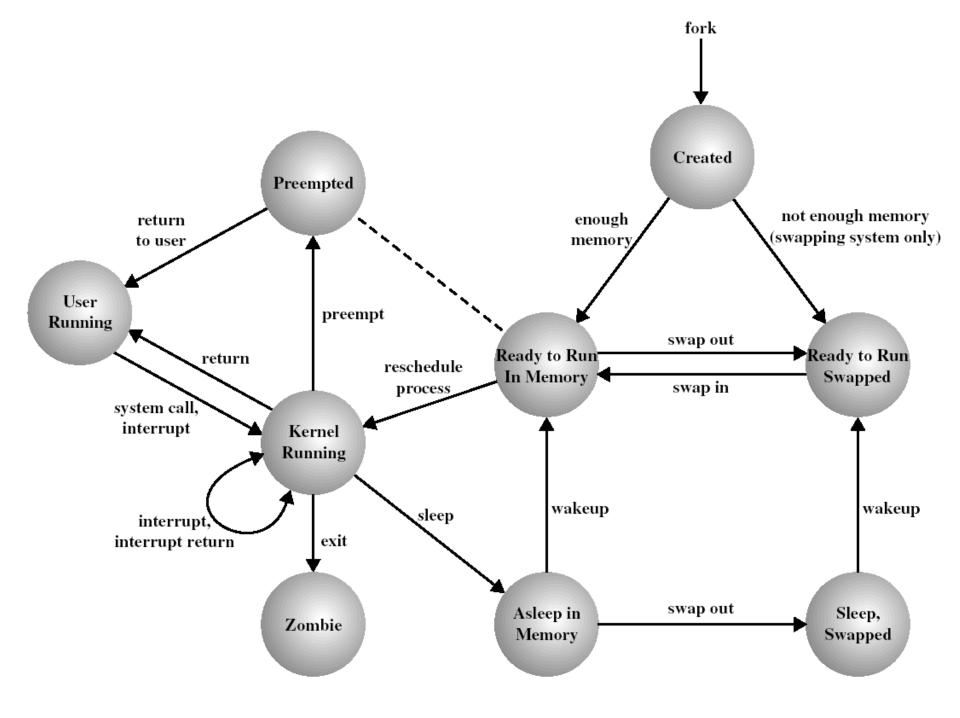
#### **Evaluation of CPU**



Case Study Unix Process Management

#### **UNIX Process States**

User Running	Executing in user mode.
Kernel Running	Executing in kernel mode.
Ready to Run, in Memory	Ready to run as soon as the kernel schedules it.
Asleep in Memory	Unable to execute until an event occurs; process is in main memory (a blocked state).
Ready to Run, Swapped	Process is ready to run, but the swapper must swap the process into main memory before the kernel can schedule it to execute.
Sleeping, Swapped	The process is awaiting an event and has been swapped to secondary storage (a blocked state).
Preempted	Process is returning from kernel to user mode, but the kernel preempts it and does a process switch to schedule another process.
Created	Process is newly created and not yet ready to run.
Zombie	Process no longer exists, but it leaves a record for its parent process to collect.



#### Zombies

- A process which has finished the execution but still has entry in the process table to report to its parent process is known as a zombie process.
- A child process always first becomes a zombie before being removed from the process table.
- The parent process reads the exit status of the child process which reaps off the child process entry from the process table.
- zombie is not really a process as it has terminated but the system retains an entry in the process table for the nonexisting child process.
- A zombie is put to rest when the parent finally executes a wait().

#### A C program to demonstrate Zombie Process.

// Child becomes Zombie as parent is sleeping
// when child process exits.
#include <stdlib.h>
#include <sys/types.h>
#include <unistd.h>
int main()
f

#### {

// Fork returns process id
// in parent process
pid\_t child\_pid = fork();

```
// Parent process
if (child_pid > 0)
    sleep(50);
```

// Child process
else
 exit(0);

return 0;

#### A C program to demonstrate Zombie Process.

// Child becomes Zombie as parent is sleeping

// when child process exits.	Activities ▷ Terminal - Tue 12:10 ●							
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ł	5 1 .	):00 top						
// Fork returns process id		):00 ps						
// in parent process	[chhaya@localhost ~]\$ cc zombie.c [chhaya@localhost ~]\$ ./a.out							
	in child process <sup>2</sup>							
pid_t child_pid = fork();	[2]+ Stopped ./a.out							
	[chhaya@localhost ~]\$ ps -l							
		TIME CMD						
// Parent process		):00 bash						
if (child_pid > 0)		0:00 top						
· <u> </u>	5 1 7	0:00 a.out 0:00 a.out <defunct></defunct>						
sleep(50);		0:00 ps						
	[chhaya@localhost ~]\$ fg	1.00 p3						
	./a.out							
// Child process	in parent process[chhaya@localhost ~]\$ ps -l							
else		TIME CMD						
		0:00 bash						
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	0 R 1000 3160 2530 0 80 0 - 35810 - pts/0 00:00 [chhaya@localhost ~]\$	0:00 ps						
	[emaya@cocacilosc ~]\$							

return 0;

}

# Orphans

- A process whose parent process no more exists i.e. either finished or terminated without waiting for its child process to terminate is called an orphan process.
- When a parent terminates, orphans and zombies are adopted by the init process (process-id -1) of the system.

#### A C program to demonstrate Orphan Process.

// Parent process finishes execution while the // child process is running. The child process // becomes orphan. #include<stdio.h> #include <sys/types.h> #include <unistd.h>

```
int main()
```

{

}

```
// Create a child process
int pid = fork();
```

```
if (pid > 0)
   printf("in parent process");
```

```
// Note that pid is 0 in child process
  // and negative if fork() fails
  else if (pid == 0)
     sleep(30);
     printf("in child process");
  }
return 0;
```

#### A C program to demonstrate Orphan Process.

// Parent process finishes execution while the
// child process is running. The child process
// becomes orphan.
#include<stdio.h>
#include<stdio.h>
#include <sys/types.h>
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#### int main()

```
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```
// Note that pid is 0 in child process
// and negative if fork() fails
else if (pid == 0)
{
    sleep(30);
    printf("in child process");
}
```

```
return 0;
```

```
}
```

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#### Daemons

- Daemons are server processes that run continuously.
- Most of the time, they are initialized at system startup and then wait in the background until their service is required.
- A typical example is the networking daemon, xinetd, which is started in almost every boot procedure. After the system is booted, the network daemon just sits and waits until a client program, such as an FTP client, needs to connect.

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